

FETIX 656

May 2020





G56 is a high-competition, high-quality, 1/10-scale model car intended for persons aged 16 years and older with previous experience building and operating RC model racing cars. This is not a toy; it is a precision racing model. This model racing car is not intended for use by beginners, inexperienced customers, or inexperienced racers or by children without direct supervision of a responsible, knowledgeable adult.

Before building and operating your G56, YOU MUST read through all of the operating instructions and instruction manual and fully understand them to get the maximum enjoyment and prevent unnecessary damage. Read carefully and fully understand the instructions before beginning assembly.

Contents of the box may differ from pictures. In line with our policy of continuous product development, the exact specifications of the kit may vary without prior notice.

Take appropriate safety precautions prior to operating this model. You are responsible for this model's assembly and safe operation! Please read the instruction manual before building and operating this model and follow all safety precautions

IMPORTANT NOTES - GENERAL

- This product is not suitable for children under 16 years of age without the direct supervision of a responsible and knowledgeable adult.
- Carefully read all manufacturers warnings and cautions for any parts used in the construction and use of your model.
- Assemble this kit only in places away from the reach of very small children.
- First-time builders and users should seek advice from people who have building experience in order to assemble the model correctly and to allow the model to reach its performance potential.
- Exercise care when using tools and sharp instruments.
- Take care when building, as some parts may have sharp edges.
- Keep small parts out of reach of small children. Children must not be allowed to put any parts in their mouth, or pull vinyl bag over their head.
- Read and follow instructions supplied with paints and/or cement, if used (not included in kit).
- Immediately after using your model, do NOT touch equipment on the model such as the motor and speed controller, because they generate high temperatures. You may seriously burn yourself seriously touching them.
- Follow the operating instructions for the radio equipment at all times.
- Do not put fingers or any objects inside rotating and moving parts, as this may cause damage or serious injury as your finger, hair, clothes, etc. may get caught.
- Be sure that your operating frequency is clear before turning on or running your model, and never share the same frequency with somebody else at the same time. Ensure that others are aware of the operating frequency you are using and when you are using it.
- Use a transmitter designed for ground use with RC cars. Make sure that no one else is using the same frequency as yours in your operating area. Using the same frequency at the same time, whether it is driving, flying or sailing, can cause loss of control of the RC model, resulting in a serious accident.
- Always turn on your transmitter before you turn on the receiver in the car. Always turn off the receiver before turning your transmitter off.
- Keep the wheels of the model off the ground when checking the operation of the radio equipment.
- Disconnect the battery pack before storing your model.
- When learning to operate your model, go to an area that has no obstacles that can damage your model if your model suffers a collision
- Remove any sand, mud, dirt, grass or water before putting your model away.
- If the model behaves strangely, immediately stop the model, check and clear the problem.
- To prevent any serious personal injury and/or damage to property, be responsible when operating all remote controlled models.
- The model car is not intended for use on public places and roads or areas where its operation can conflict with or disrupt pedestrian or vehicular traffic
- Because the model car is controlled by radio, it is subject to radio interference from many sources that are beyond your control. Since radio interference can cause momentary loss of control, always allow a safety margin in all directions around the model in order to prevent collisions.
- Do not use your model:
- Near real cars, animals, or people that are unaware that an RC car is being driven.
- In places where children and people gather
- In residential districts and parks
- In limited indoor spaces
- In wet conditions
- In the street
- In areas where loud noises can disturb others, such as hospitals and residential areas.
- At night or anytime your line of sight to the model may be obstructed or impaired in any way.

To prevent any serious personal injury and/or damage to property, please be responsible when operating all remote controlled models.

Failure to follow these instructions will be considered as abuse and/or neglect.

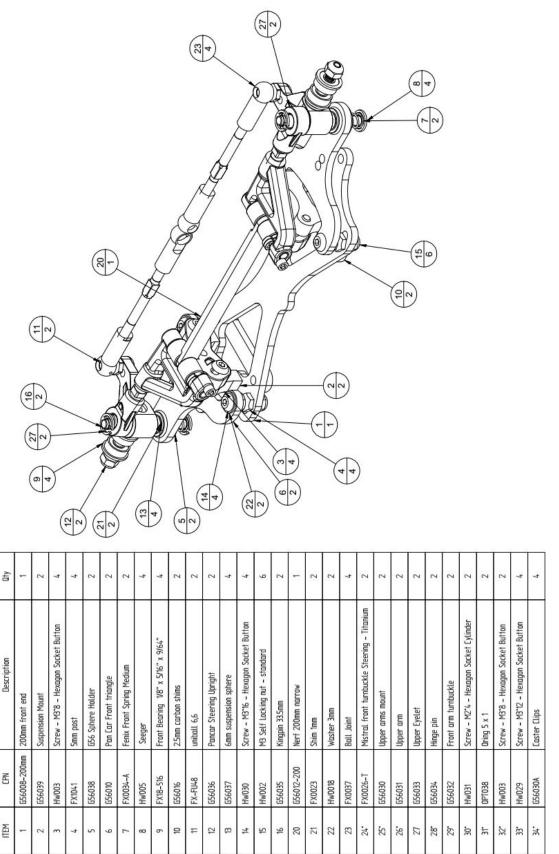
We have made every effort to make these instructions as easy to understand as possible.

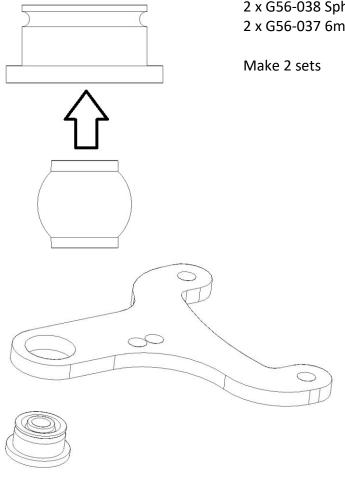
However, if you have any difficulties, problems, or questions, please do not hesitate to

contact the Fenix support team at racing@fenixwaterjet.com. Also, please visit our Web site

at www. Fenix-racing.com or www.fenixracingshop.com or https://www.facebook.com/FenixRacing.it/ the latest updates, set-up information, option parts, and many other goodies. We pride ourselves on taking excellent care of our customers.

Bag A



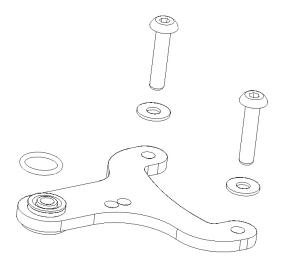


2 x G56-038 Sphere holder 2 x G56-037 6mm sphere

> Insert the group into the G56-010 front arm - Make 2 mirror sets.

Be sure that the sphere holder fit easily, you might have to enlarge the hole with some sandpaper.

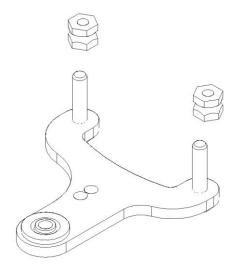
Make 2 sets mirror like

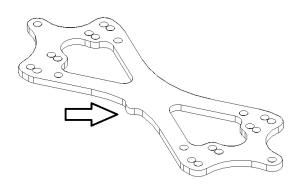


Insert the OPT-038 Oring around the sphere holder. Take 2 x HW018 M3 Washer and 2 x HW030 Me x 16mm button head screw. Make 2 sets mirror like



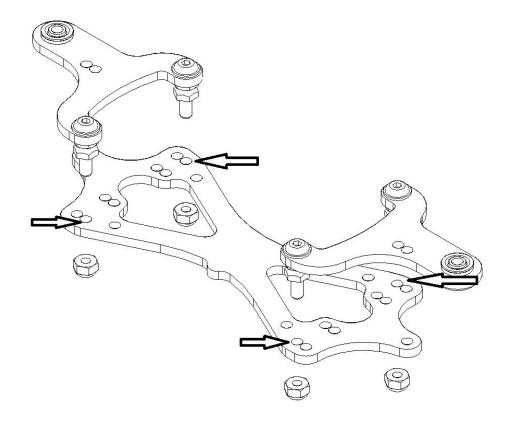
Screw the 2 FX-1041. Make 2 sets mirror like





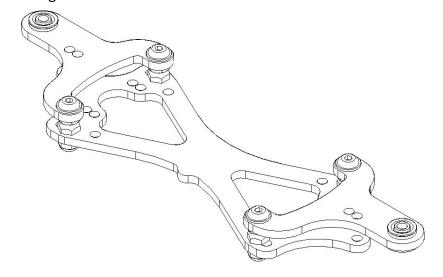
Take the G56-008 200 (or 235) front beam.

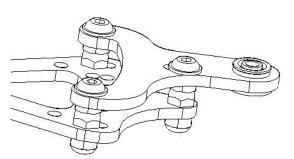
Take care of the position of the dimple, it goes toward the front of the car.





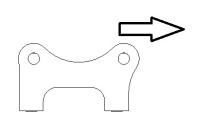
Assembly as shown – Start with the Narrow option . Tight the $4\,x$ HW002 self-locking M3 nuts



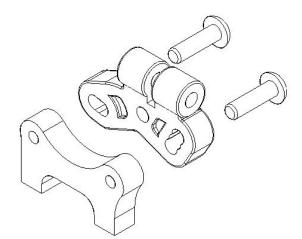


Front end tuning!
You can alter the front end
rigidity by coupling the front
end arms with the front beam.

(Option 5mm post need to be used)

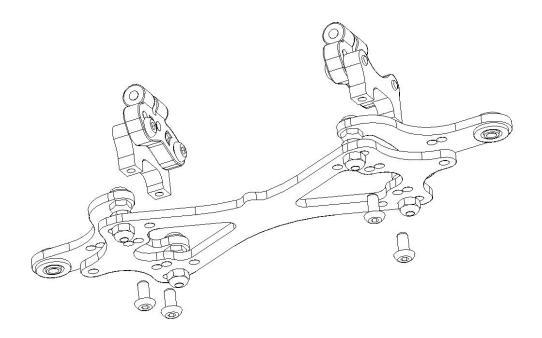


Take care of the direction for G56-039 . The arrow point the front of the car. Make 2 mirror sets.

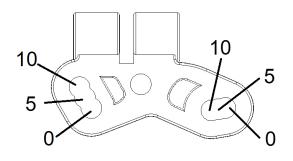


Secure the G56-030 upper arm mount to the G56-039 using 2 HW029 M3x12mm Hex button screw.

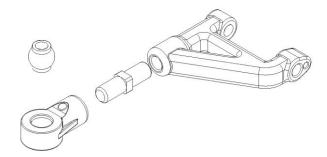
Make 2 sets mirror like



Assembly the 2 groups to the front bear with 4 x HW008 M3x8mm button screw. Use the innermost set of holes.

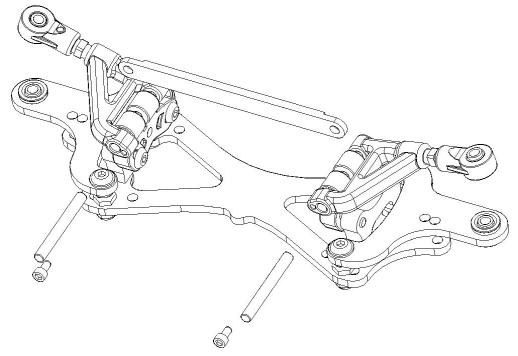


Active caster settings.
5 Degrees are default setting.

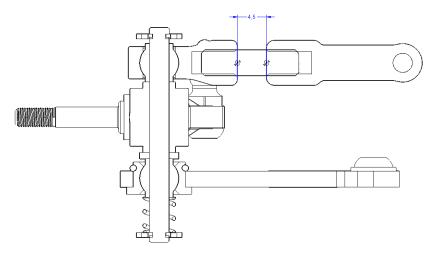


G56-031 arm – G56-033 eyelet-G56-032 turnbuckle G56-037 sphere

Make 2 sets

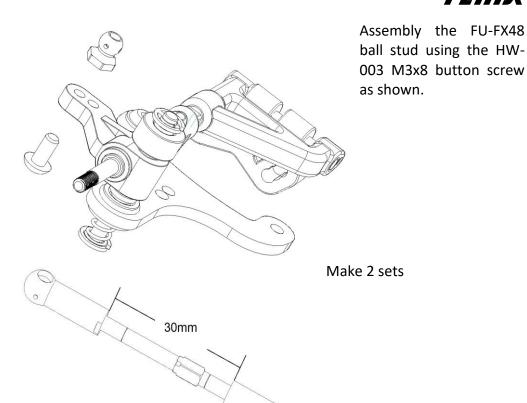


Slide the G56-012 Narrow front beam into the upper arm mounts, then insert the G56-034 hinge pins and secure them with the HW031 M2x4 screw



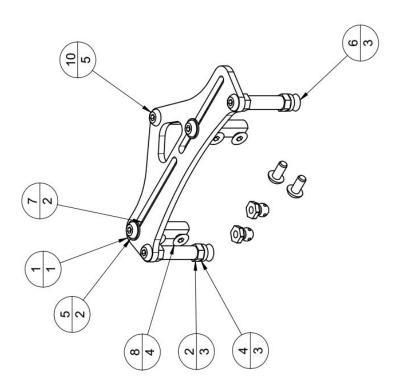
Set the distance at 4.5mm. Assembly the steering upright group as shown. Use the provided shims to fine tune the front ride height.



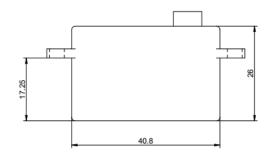


Keep the 2 x G56-015 for further step

Bag B

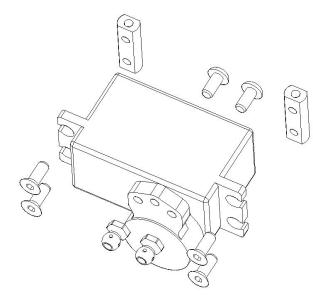


QTY	1	3	t 2	3	2	3	2	7 +	2	5 +
Description	servo holder	20mm Alu post	Screw – M3'6 – Hexagon Socket Button	Shim 1,5mm	Washer 3mm	Screw – M310 – Hexagon Socket Countersunk	Mistral Servo Mount	Screw – M3'6 – Hexagon Socket Countersunk	nniball 6,6	Screw – M3*8 – Hexagon Socket Button
CPN	656011	FX0052	HW008	FX0063	HW0018	HW004	FX0022	HW012	FX-FU48	HW003
ITEM	1	2	3•	7	5	9	7	8	.6	10



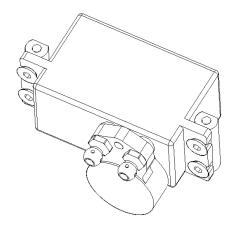
Servo and servo saver are not included, model need a low profile servo.

Note the dimension of the servo suggested



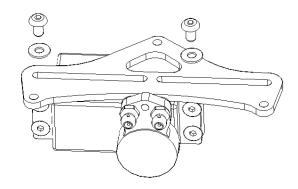
Use the 2 x HW003 M3x8mm button to secure the FX-FU48 to the servo saver.

Use the 4 x HW008 M3x8 countersunk screw to fix the FX022 servo mount

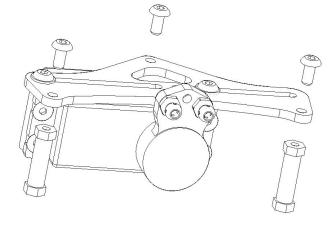


Assembled group. Servo saver should be vertical when servo is neutral.

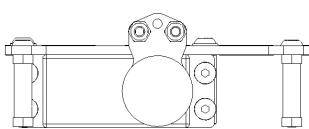
Using the 2 x HW0018 washer and 2 x HW008 M3x6 Button, fix the servo group to the G56-011 servo holder



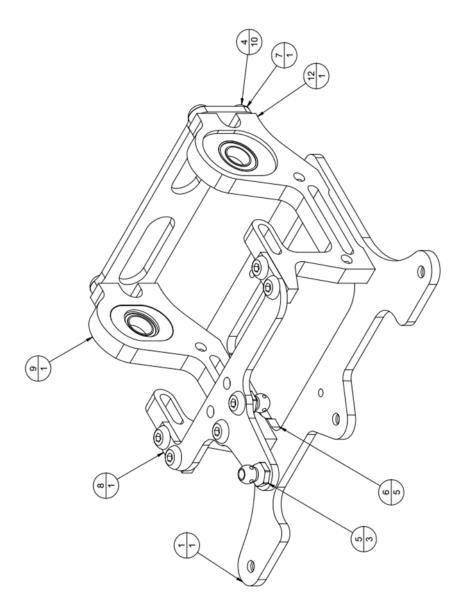
Fix the 3 x FX0052 20mm post to the servo holder using 3 x HW003 M3x8 button screw.



Be sure that the servo is centered. Keep the provided 3 x 1.5mm shims and screws for a further step.

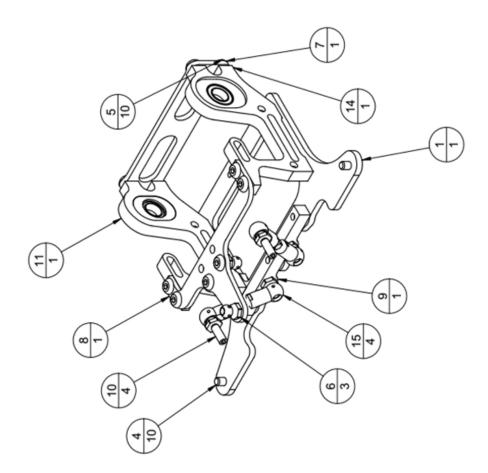


Bag C -Pivot



ITEM	CPN	Description	QTY
1	G56017-200 PMP	Motor Pod Pivot - 200mm	1
4	нw008	Screw - M3*6 - Hexagon Socket Button	10
5	FX-FU48	uniball 6,6	3
9	HW012	Screw - M3*6 - Hexagon Socket Countersunk	5
7	G56021	motor brace 200 mm	1
8	G56019-200 shock	Shock holder 200 mm	1
6	MH-PAN A	Motor holder - motor side	1
10*	FX0048	Ride height adjuster - (for FX050 motor holder)	2
11*	FX14-38	Ball Bearing Flanged 3/8"x1/4"	2
12	MH-PAN B	Motor holder pancar	1

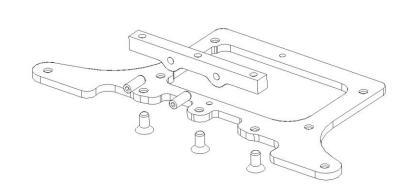
Bag C -Vlink



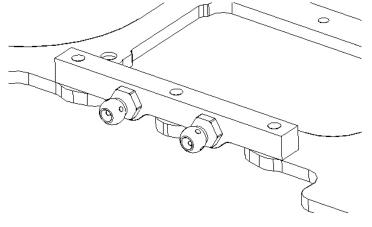
QTY	1	10	10	3	1	1	1	4	1	2	2	1	4	2	4
Description	Motor Pod VLINK - 200mm	Screw - M3*6 - Hexagon Socket Countersunk	Screw - M3*6 - Hexagon Socket Button	uniball 6,6	motor brace 200 mm	Shock holder 200 mm	V-link 2 Motor pod	Grub screw M3*8	Motor holder - motor side	Ride height adjuster - (for FX050 motor holder)	Ball Bearing Flanged 3/8"x1/4"	Motor holder pancar	Ball Joint - SHORT	Titanium Tie Rod 15mm	uniball 6,6
CPN	G56023-200VL	HW012	HW008	FX-FU48	G56021	G56019-200 shock	V-link2	HW013	MH-PAN A	FX0048	FX14-38	MH-PAN B	FX0037	TR-15	FX-FU48
ITEM	1	4	5	9	7	8	6	10	11	12*	13*	14	15	16*	17*



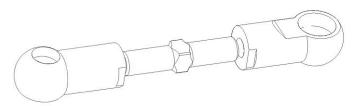
Note: If you're assembling the pivot version, skip the 4 next step



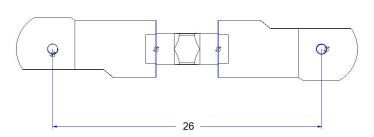
Using 3 x HW012 M3x6 countersunk screw fix the V-link2 to the motor pod.
Insert 2 x HW013 M3x8 grub screw into the V-link 2. Keep about 4 mm of thread out.



Fix the 2 FX-FU48 to the protruding grub screw.

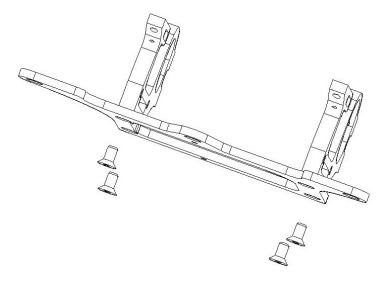


Build 2 set of link using 2 x TR15 and 4 FX0037 - short



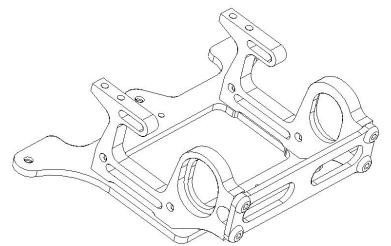
Keep this dimensions.
Fix the link over the V-link2

Note: This set of instruction is the same for Pivot and V-link version, both 200mm and 235mm.



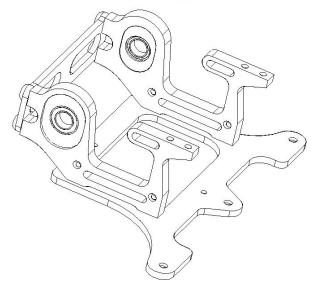
Using 4 x HW012 countersunk screws, fix the motor holder to the motor pod.

Tight the screws evenly using an "X" pattern



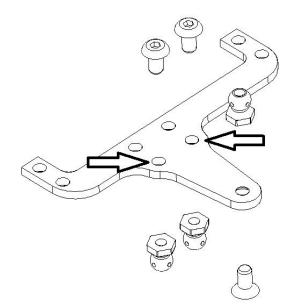
Fix the G56-021 brace to the group using 4 x HW008 M3x6 button screw.

Tight the screws evenly using an "X" pattern

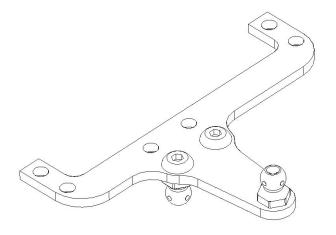


Insert the ride height adjuster and the flanged bearings

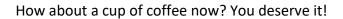




Install the FX-FU48 in the first set of holes. This is set of holes is intended for the pivot version, the other set is intended for the V-Link version.



Wait to install the shock holder to the motor group.

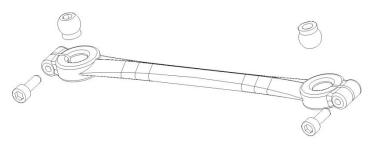






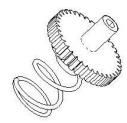
Bag D - Pivot + V-link - Common parts

Note: the following parts are common in both version,



Prepare 2 sets – note the position of the spheres.

Use 2 x HW0014 M2x 6 screws and 2 x FX002 spheres each



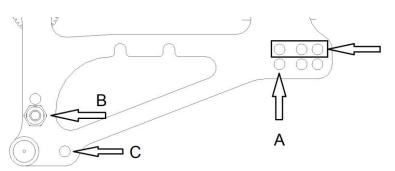
Grub screw M3 x 8 Prepare 2 set as shown.



Note: spring holder might have 2 different shape. Hex one or round one.



Assembly the 2 side dampers as shown



Link options:

Inner set = 200mm version

Outer set = 235mm version

A – Fenix links default, other holes allow to use longer links.

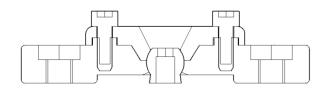
B – default side damper location

C – default body post location

Pivot rear end

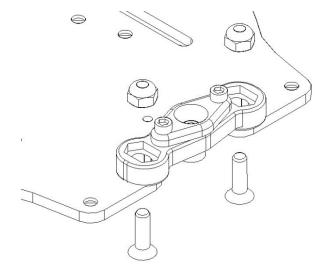
	(P)										0		(38)	(25)	$\bigoplus_{i=1}^{n}$		(18)	88	2)									
								10	/	•	0	A		0			,	\bigcirc	ΔT	4	2		2	2	2	2	7	2	4
					(%)				_	_	•	000							Description	Screw - M2*6 - Hexagon Socket Cylinder	Screw - M3*6 - Hexagon Socket	Countersunk	Side Link kit - spring holder	Side spring	Grub screw M3*8	Damper body	Damper Piston	Grub screw M3*10	Ball Joint - SHORT
							202	•	/	/	æ_	/.		()		//			CPN	HW014	HW012		FX0015	FX0033	HW013	FX0042-A	FX0042-B	HW032	FX0037
							(=	2		(Ð-	(1						32*	33		34*	35	36*	37*	38*	39*	40
QTY	1	9	00	2	9	14	2	2	2	2	2	4	2	1	2	2	00	2	T.	1	1	1	2		-	2		4	2
Description	Chassis	12mm Alu post	Screw - M3*8 - Hexagon Socket Countersunk	uniball 6,6	Screw - M3*6 - Hexagon Socket Countersunk	M3 Self Locking nut - standard	Shim 2,5mm	Body bost	Side Wing pivot version	Body bost	Screw - M3*6 - Hexagon Socket Button	Screw - M3 x 12 - Hexagon Socket Countersunk	Tapered washer	Pancar bumper	Screw - M3*12 - Hexagon Socket Button	Shim 2mm	Screw - M3*8 - Hexagon Socket Button	Screw - M3*10 - Hexagon Socket Countersunk	High Body support	Suspension Sphere - link	Side link kit - Pivot	Side link kit - cover	Screw - M2*6 - Hexagon Socket	Cylinder	Screw - M3*6 - Hexagon Socket Countersunk	Screw - M3*10 - Hexagon Socket	Countersunk	Suspension Sphere - link	Side Links kit - link
CPN	G56001	FX0052	HW007	FX-FU48	HW012	HW002	FX0073	HW015	G56002	HW015	HW008	HW026	FX10B	900959	HW029	FX02009	HW003	HW004	656005	FX022	FX0015	FX0015	HW014		HW012	HW004		FX022	FX0015
ITEM	1	2	3*	2	9	7	*8	6	10	11	13*	14	15	16	18	*02	21	22	23	24*	25	*97	27*		28*	*62	Access of the second		31*

Note: If you're assembling the V-Link version, skip this section and go to V-link Rear End



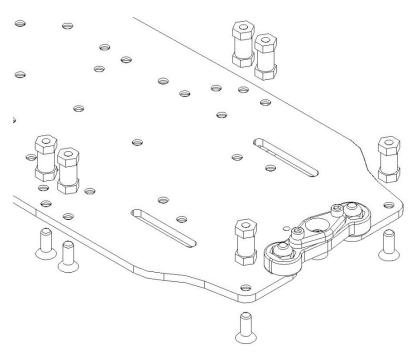
Note: Put a drop of shock oil over the sphere and carefully tight the M2x6 screws. The sphere should move easily, but w/o too much play.

Use 2 x HW0014 M2x 6 screws and 1 x FX002 sphere



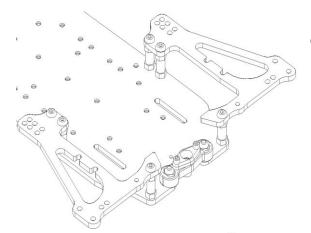
Fix the pivot group to the chassis using 2 x HW004 M3x10 countersunk screws and 2 HW002 M3 self-locking nut.

Do not tight them fully, as you need to "center" the pivot group, once installed the side links.

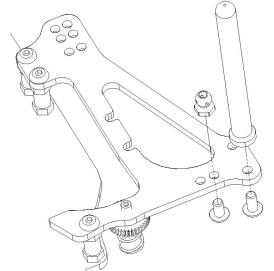


Take the 6 x FX0052 12mm post and 6 x HW007 M3x8 countersunk screw and assembly as shown.





Using 6 x HW003 M3x8 button screws fix the 2 X G56-002 side wings



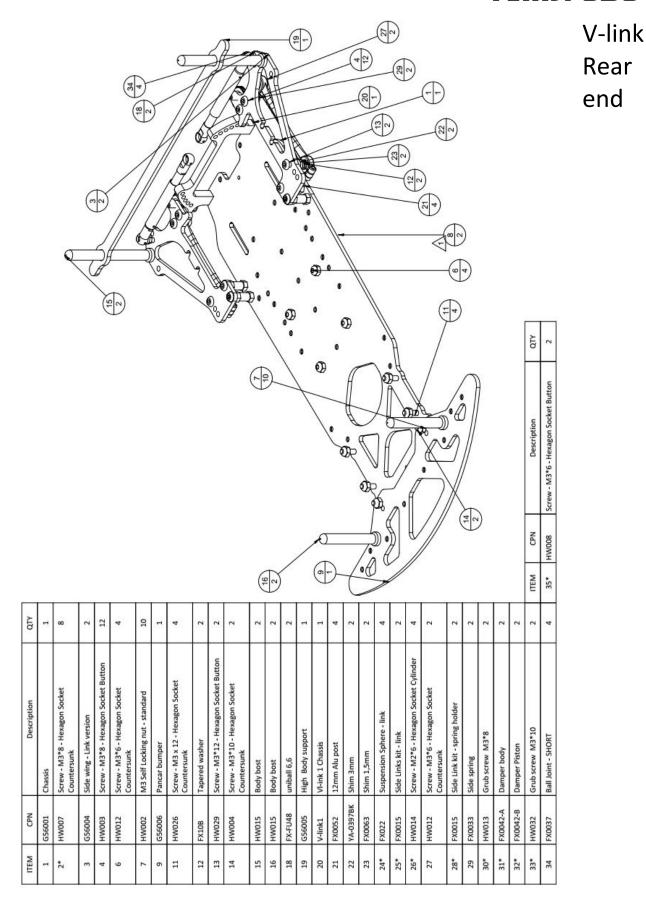
Assembly the FX-FU48 using 1 x HW008 3x6 button screw, the body post using 1 x HW003 3x8 button screw.

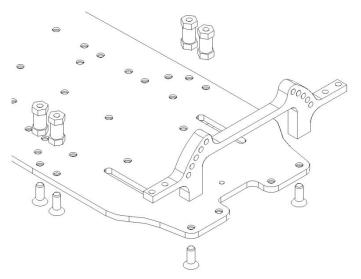
Use special attention when "thread" the grub screw in the carbon fibre, lubricate the grub screw often during the operation and insert it slowly.

If you're assembling the Pivot version, please – skip to

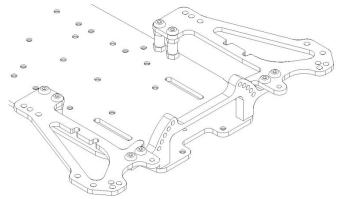
Bag D − Common instructions → page 25

FENIX G56

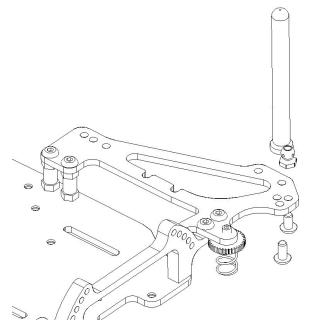




Take the 4 x FX0052 12mm post, the V-link 1 and 6 x HW007 M3x8 countersunk screw and assembly as shown.

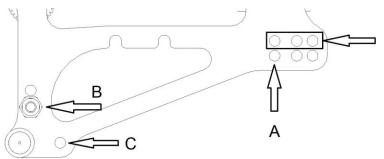


Using 8 x HW008 M3x8 button screws fix the 2 X G56-004 side wings



Assembly the FX-FU48 using 1 x HW008 3x6 button screw, the body post using 1 x HW007 3x8 button screw.

Use special attention when "thread" the grub screw in the carbon fibre, lubricate the grub screw often during the operation and insert it slowly.



Link options:

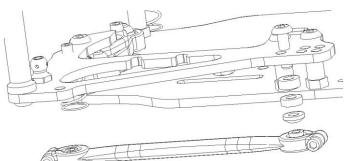
Inner set = 200mm version

Outer set = 235mm version

A – Fenix links default, other holes allow to use longer links.

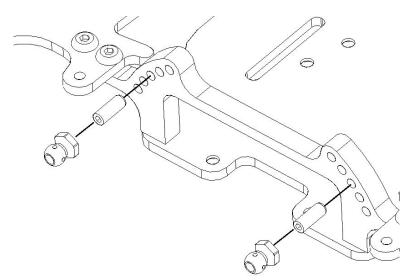
B – default side damper location

C – default body post location



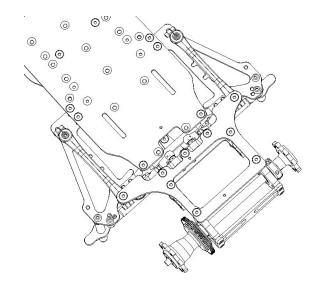
Insert the HW0029 M3x12 in the proper "A" hole, then slide over 1 x 2.5mm and 1 x 2mm shims, plus the tapered washer (cone downward).

Install the link assembled previously

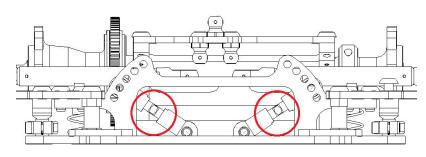


From Bag C, insert 2 x HW013 grub screw, leave approximately 4mm out and screw on the 2 FUFX48.

Please, check in the tech section about the V-link settings.



Fix the short link between V-link 1 and V-link2 Using 2 x HW006 M3x6 countersunk screw (from bag C), you can now install the link to the motor pod group.



for some explicative video.

https://www.youtube.com/channel/UCDZqN09hr2Eal7qHCMjUcjQ

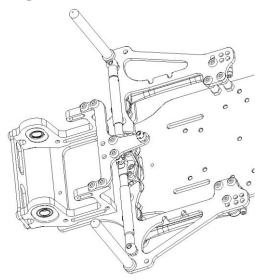
Now, lay the car on a flat setup board and make the final fine tuning of the links length.

Chassis and motor pod must lay flat on the setup board.

Take the proper time for this setting.

Check our channel on Youtube

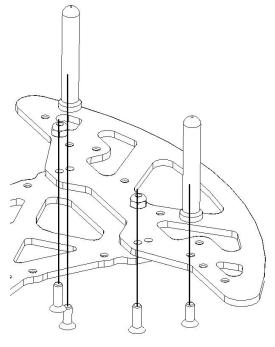
Bag D – Common instructions



Using the parts remaining from Bag C Install now the 2 dampers and the shock holder using 4 x HW008 3x6 button screw.

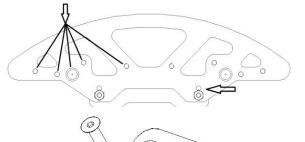
Note:

When use the V-link configuration, according the position of the V-link, dampers position might have to be relocate on the upper side of the shock holder.

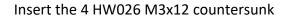


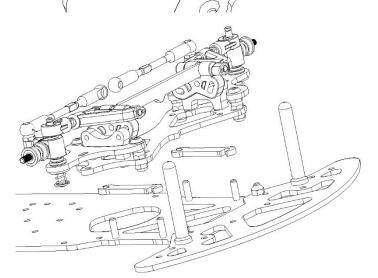
Fix the G56-006 bumper and fix it using 2 x HW004 M3x10 countersunk and 2 x HW002 M3 self-locking nut.

Fix the bodypost using 2 x HW007 M3x8 countersunk screws.

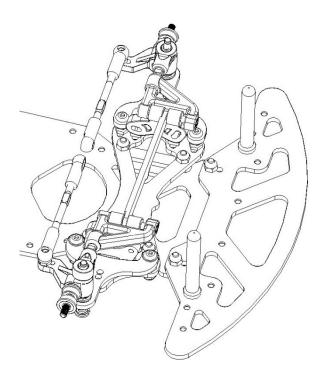


Please note that the bumper is having 2 possible locations and there 5 alternative possible for the front posts

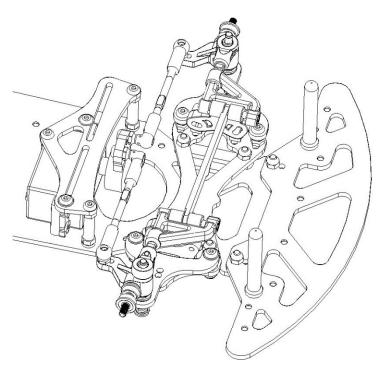




Take the 2 G56-016 2.5mm shims from Bag A, insert over the screws and slide the complete front end over the chassis. There are also 1mm and 0.5mm shims to set the front ride height.



Fix the front end using 4 x HW002 M3 self-locking nut.

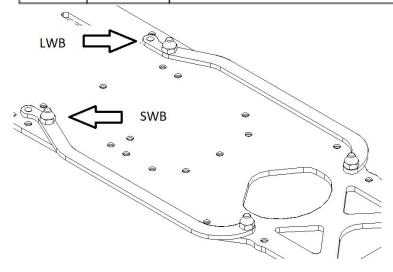


From bag B, use HW004 M3x10 countersunk screw and fix the Servo holder group.

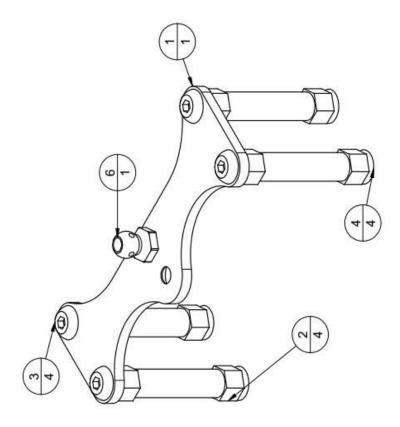


Bonus! Chassis Stiffner

ITEM	CPN	Description	Qty
1	G56001	Chassis	1
2	G56007	Chassis stifferner	2
3	HW004	Screw - M3*10 - Hexagon Socket Countersunk	4
4	HW002	M3 Self Locking nut - standard	4

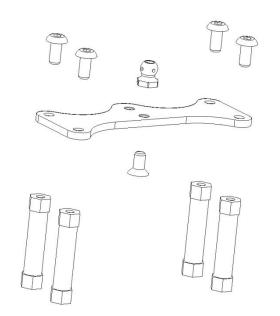


Bag E



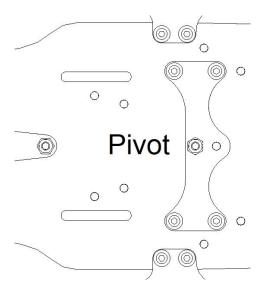
CPN	Description	QTY
656-003	Shock holder	1
FX0054	Post 26mm	4
HW003	Screw - M3*8 - Hexagon Socket Button	4
	Screw - M3*8 - Hexagon Socket Countersunk	4
HW012	Screw - M3*6 - Hexagon Socket Countersunk	1
FX-FU48	uniball 6,6	1

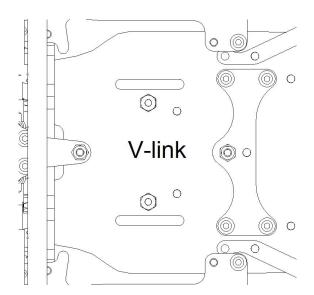


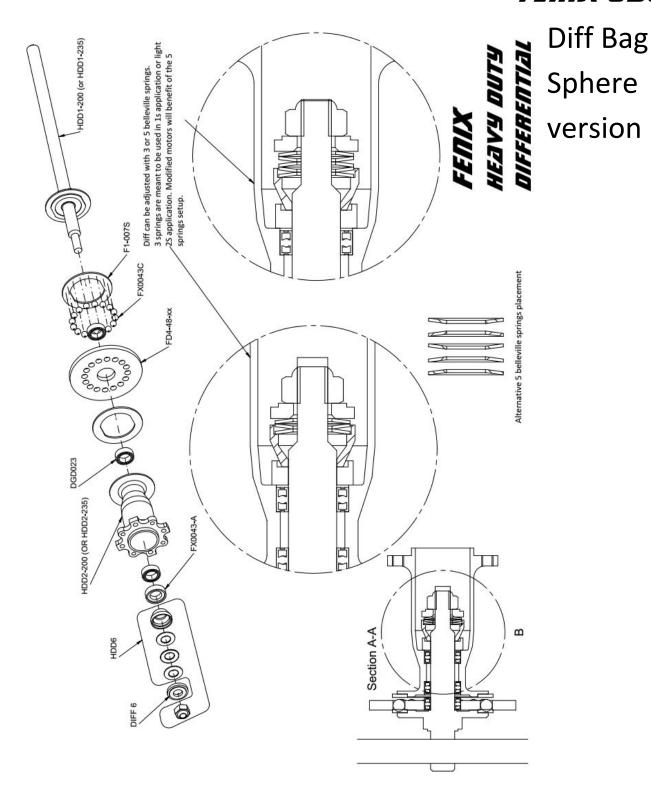


Fix the 4 by 26mm post using 4 x HW003 M3x8 button screw.

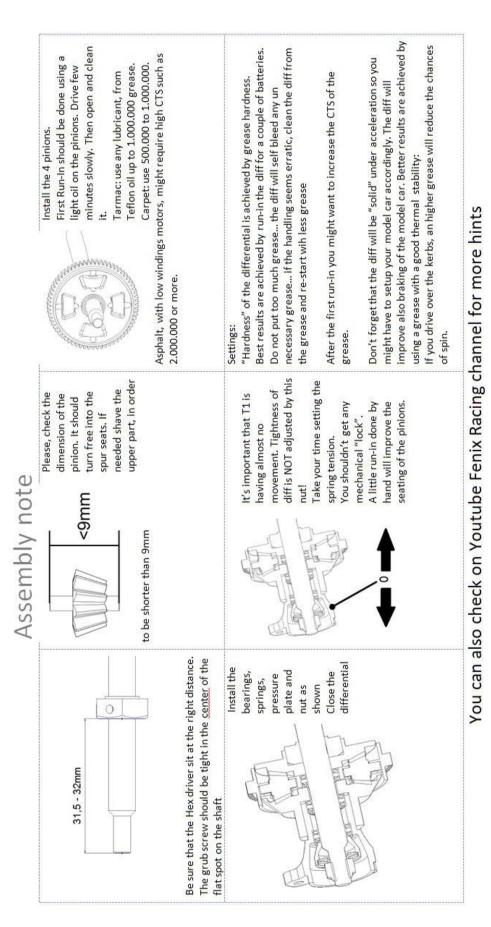
Fix the FX-FU48 using 1 x HW012 M3x6 countersunk screw according your car version.



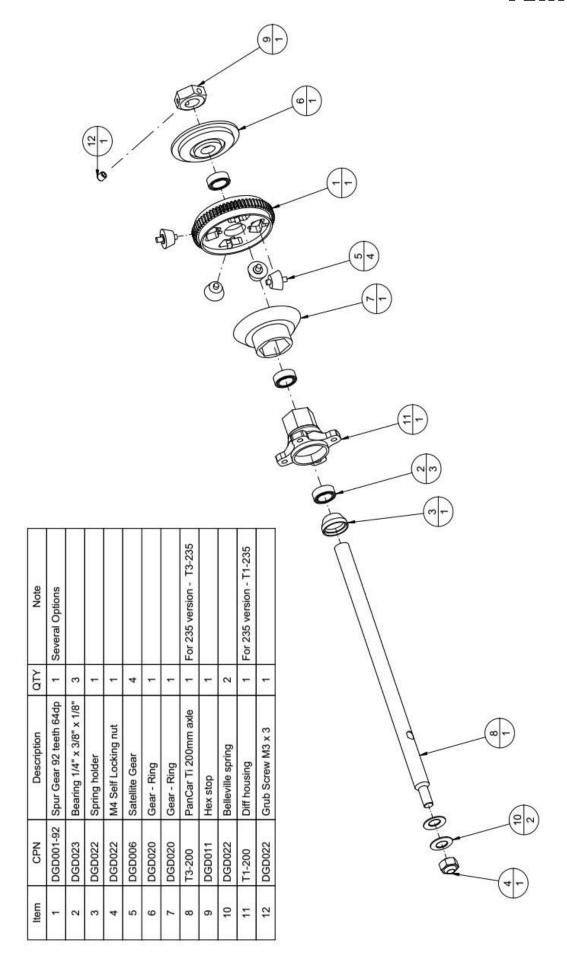


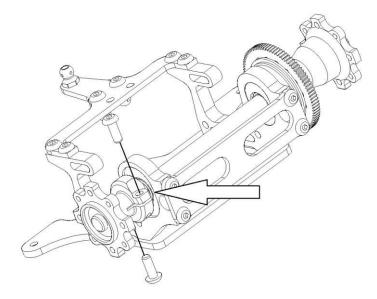


Diff
Bag
Gear
Diff
version



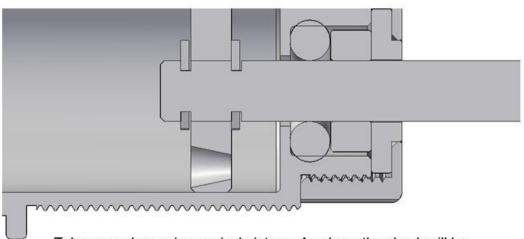
FENIX G56





Slide the left hub HDD4 on the rear axle, leave 0.1-0.2mm of axial play. Clamp it on the axle using 2 x HW004 3x10 button screws

Shock Bag



Take care when using conical pistons. As show, the shock will be harder in compression and softer in extension



Assembly the shock as show,



Tech area

G56 allow several different major setting.

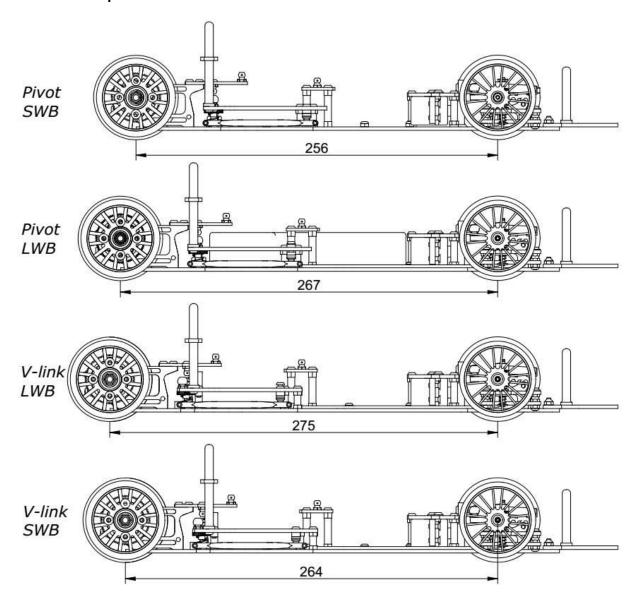
Pivot and V-link, you can convert from one version to the other, with a minimal amount of parts.

Pivot: it's supplied with the SWB chassis, can carry lipos shorty only, if you need to carry standard touring lipos, you need to use the optional LWB chassis.

Best suited for carpet and indoor

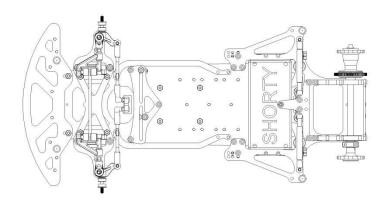
V-link: it's supplied with the LWB chassis, can carry standard lipo touring, if you race on small tracks, you might fit the SWB chassis to get a more agile car but then, you cannot carry the touring lipos.

Best suited for open outdoor circuits

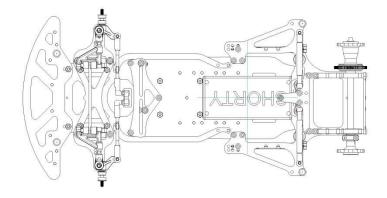




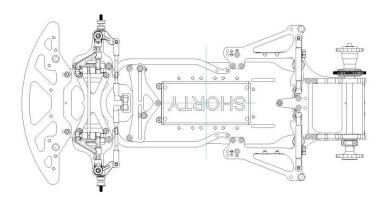




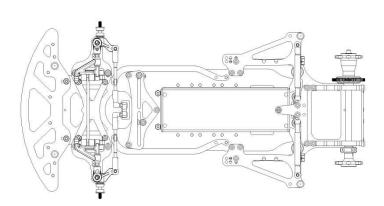
Shorty inline rear position



Shorty inline front position



Big lipo: only on LWB chassis version





V-Link suspension has the unique ability to alter the roll centre

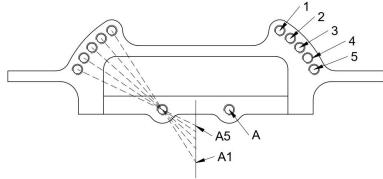
can

significantly the amount of rear grip by changing the roll centre position. Best starting position is

alter

position. You

Α3



A5 position = High Roll centre position A1 position = Low roll centre position

The 2 link connection link must have the same length. Check the Fenix Youtube channel for an easy system to set the tierod length.

https://www.youtube.com/watch?v=SEwNQcn12A0

Millimetre per revolution aka Rollout

Pancar (1/10 - 1/12) are using foam tires, where ratio need to be adjusted after each run, the system is MM (millimeter) Per Revolution aka Rollout.

It means you want to check how many mm the motor move each revolution.

You need to know:

Diameter of tire (easy take your Vernier and check it...):

Spur size and Pinion size

Diameter x 3.14 = perimeter Tire diameter 56 x 3.14 = 175.84mm ok... keep it.. Spur / pinion 81/26 = 3.11

175.84/3.11 = 56.54mm

Each turn of your motor, your car will travel 56.54mm

Rule of thumb: 13.5 – 2S – to timing/blinky mode Indoor between 50-55mm, Outdoor between da 65-75, Huge 1/8 tracks 80mm

Rule of thumb: 4.5 - 2S

Outdoor starting point 45mmpr check temp often during the setup

There are a bunch of free app to be downloaded on your smartphone...

Check for instance "Gears", made by Nor-Cal Hobbies.

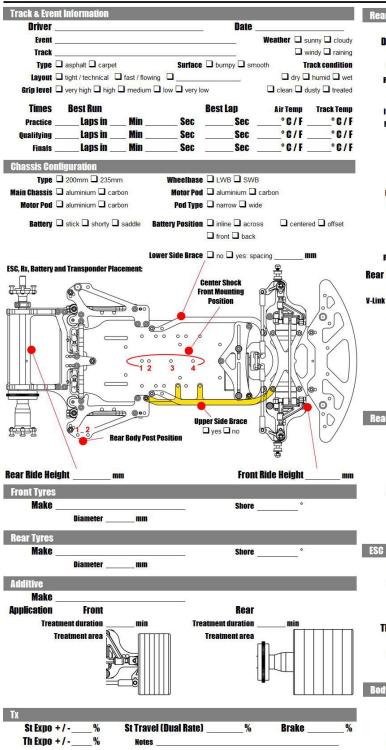
Here you can download "Gears"

https://play.google.com/store/apps/details?id=com.seamusoft.gears&hl=it



Front Suspension

Springs \square progressive \square linear	Di-rate L	Kate / Color		
Make Fenix Asso CF	RC 🗖 Xray 🗖	Droop /	Preload	mn
Camber L+/- ° R+/-	0			
Toe in/out <u>-/+ </u>		Brace ☐ fixed	adjustable:	
		Brace	spacer	
Steering Servo Saver 🖵 large	mid small	Inner steerii	ng link 🚗	
Servo Position 🔲 left 🗆	ight right	mounting	holes 💮	
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Ackermann Shims Servo Servo mount	T. Control of the Con			
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Bumpsteer Shims	mm	Ride height S	pacer	mı
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Track width shims		romei ioni centei	SIIIIIS	
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	Caster Bulkhead Caster Clip position 3.0° 4.6° 6.2° 8.0° 9.6° 11.2° 13.0° Reactive Caster	FF thin, thick thin thick think thin, thick thin think thin, thick	FF	- hick hin



Rear Suspe	nsion
Side	Type ☐ tubes ☐ side shocks Preload mm
Damper	Spring Type CRC AE Corally Xray
	Rate / Color
	nock Oil Weight wt / cst
Rebound	□ none □ 25% □ 50% □
Inner Tub	e/Shock Outer Outer
Mounting	4
	Mounting Position
	Position Position
Contor	
Center Shock	
SHUGK	Rate / Color Preload Preload mm
SI	nock Oil Weight wt/cst
	□ 1-hole □ 2-hole □ 3-hole □ no-hole □
Rebound	□ none □ 25% □ 50% □mm
Rear Link Set	Type D pivot D v-link
Upper	Lower
V-Link Position	V-Link Position
	O ₄ C
	Side link inclination (rear axle bumpsteer, v-link only)
	VOI ← OI ←
	Rear Inclination (△ Front./. Rear) Front
	mmmm
Rear Axie	mmmm
Rear Axie Axie	mmmmmm Make
TOTAL STREET,	Make □ titanium □ graphite Differential □ sphere □ gear Gear Diff Oilwt/cst
Axie	Make ☐ titanium ☐ graphite Differential ☐ sphere ☐ gear
Axie	Make □ titanium □ graphite Differential □ sphere □ gear Gear Diff Oilwt/cst
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Axle Traci Height	Make titanium graphite Differential sphere gear Gear Diff Oil wt / cst Diff balls ceramic carbide steel steel
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Axle Traci Height	Make titanium graphite Differential sphere gear Gear Diff Oil wt / cst Diff balls ceramic carbide steel k Width Spacer left mm right mm Adjuster # #0 #1 #2 #3 #4 Pitch 64dp 48dp Rollout Pinion T
Axle Traci Height	Make titanium graphite
Axle Traci Height Spur	Make titanium graphite
Axie Traci Height Spur ESG Make	Make titanium graphite Differential sphere gear Gear Diff Oil wt / cst Diff balls ceramic carbide steel k Width Spacer left mm right mm Adjuster # #0 #1 #2 #3 #4 Pitch 64dp 48dp Rollout Pinion T Size T Gear Ratio : Final Rollout mm Mode blinky open
Traci Height Spur ESG Make Brake	Make titanium graphite Differential sphere gear Gear Diff Oil wt / Cst Diff balls ceramic carbide steel k Width Spacer left mm right mm Adjuster # #0 #1 #2 #3 #4 Pitch 64dp 48dp Rollout Pinion T Size T Gear Ratio : Final Rollout mm Mode blinky open Strength % Brake Frequency kHz
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Axle Tract Height Spur ESC Make Brake	Make titanium graphite Differential sphere gear Gear Diff Oil wt / cst Diff balls ceramic carbide steel k Width Spacer left mm right mm Adjuster # #0 #1 #2 #3 #4 Pitch 64dp 48dp Rollout Pinion T Size T Gear Ratio : Final Rollout mm Mode blinky open Strength % Brake Frequency kHz to / Drag Brake % Initial Brake 0% = DragBrake % 64dp %
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Axle Tract Height Spur ESC Make Brake Au	Make titanium graphite Differential sphere gear Gear Diff Oil wt / cst Diff halls ceramic carbide steel k Width Spacer leftmm rightmm Adjuster # #0 #1 #2 #3 #4 Pitch 64dp 48dp Rollout PinionT SizeT Gear Ratio _: Final Rolloutmm Mode blinky open Strength% Brake FrequencykHZ to / Drag Brake% Initial Brake 0% = DragBrake % Brake Curve linear Brive FrequencykHZ Throttle Curve linear Brive FrequencykHZ
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Axle Traci Height Spur ESC Make Brake Au Throttle Notes Body Make	Make titanium graphite Differential sphere gear Gear Diff Oil wt / cst Diff balls ceramic carbide steel k Width Spacer left mm right mm Adjuster # #0 #1 #2 #3 #4 Pitch 64dp 48dp Rollout Pinion T Size T Gear Ratio : Final Rollout mm Mode blinky open Strength % Brake Frequency kHz to / Drag Brake % Initial Brake 0% = DragBrake % Brake Curve linear